

ABSTRACT OF THE DISCLOSURE

A driving controller is adapted for controlling driving of a plurality of driving units physically connected with one another, at least one of which includes a driving member frictionally engaged with a driven member. It is detected whether the driven member is being driven at a predetermined time. The unit including the driving member and another driving unit are driven at a predetermined timing when the detecting circuit detects the driven member is not driven at the predetermined time. The driven member and the driving member can be easily released from an adhered state.